

# AMC100

1013508

## Technical Specifications

|                                 |   |
|---------------------------------|---|
| <b>Modes of Operation</b>       |   |
| open loop positioning           | stepping signals for ECS positioners  |
| closed loop positioning         | closed loop control for ECS/NUM positioners                                   |
| remote operation                | Ethernet Port and USB (with adapter)  |
| <b>Size and Dimensions</b>      |   |
| chassis                         | 22 x 22 x 4.5 cm <sup>3</sup>   |
| weight                          | 2 kg  |
| <b>Controller Hardware</b>      |   |
| power supply                    | 100/115/230V, 50 .. 60 Hz   |
| connector                       | IEC inlet   |
| connection cable (ELE - POS)    | 1 per axis, length: 2m  |
| <b>Software Drivers</b>         |   |
| Windows, Linux                  | DLL, LabVIEW™, JSON<br>Stand-alone application for Windows XP™, 7™, 8™, 10™   |
| <b>Output Signals</b>           |   |
| output connectors               | 26-Pin SubD connector   |
| output voltage range            | stepping : 0 .. 45 V; fine positioning : 0..45 VDC                            |
| frequency range                 | stepping : 0 .. 5 kHz (1 axis); stepping : 0 .. 2 kHz (3 axes simultaneously) |
| output current                  | stepping : max > 16 A peak  |
| maximum capacitance load        | 2 µF  |
| output noise                    | < 5 mVpp (500 kHz bandwidth)  |
| resolution of signal generation | 680 µV (16 bit)   |
| <b>Trigger Signals</b>          |   |
| trigger level definition        | LVDS, LVTTTL  |
| input trigger                   | 1 per axis  |
| trigger interface               | GPIO - port   |
| <b>Features and Upgrades</b>    |   |
| /PRO feature                    | enhanced functionalities and control for closed loop operation                |
| /IO feature                     | realtime interfacing with external signals (through GPIO port)                |
| /RC remote control feature      | wireless control of nanopositioners   |
| AMC/IDS closed loop feature     | interferometric position control using attocube's IDS3010                     |
| Rotation Compensation feature   | Feed-forward runout compensation of a rotator by two xy-stages                |

